

# FANUC Robot M-420iA/421iA



## 特点

- 这是一款为物流系统的机器人化做出贡献的物流智能机器人。
- 可根据系统布局，选择最佳的轴配置类型。  
FANUC Robot M-420iA : 4轴型  
FANUC Robot M-421iA : 2轴型
- 具有最大3,000次/小时的搬运能力。通过活用最大50kg的可搬运能力，一次取出多个产品，从而提高搬运作业效率。
- M-420iA/M-421iA是由搭载了多种智能化功能的最新式的高性能控制器R-J3iC控制的。

## FEATURES

- M-420iA and M-421iA are the intelligent packing robots which contribute for robotization of packing system.
- Two types of axis configuration are available.  
FANUC Robot M-420iA : 4 axis type  
FANUC Robot M-421iA : 2 axis type
- M-420iA and M-421iA can handle up to 3000 cycles per hour. Payload capacity of max. 50 kg enables to handle multiple works at once. Throughput capacity is much improved.
- M-420iA and M-421iA are controlled by R-J3iC that is newest, high performance and having various intelligent functions.

## 应用系统

### Example of an application system



将瓶子装入瓶箱的装箱系统  
Packing system of bottles into cases

# FANUC Robot M-420iA/421iA

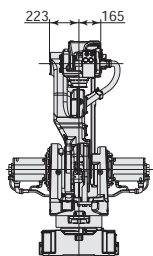
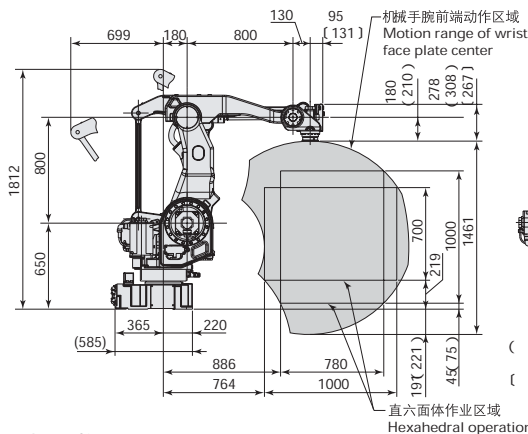
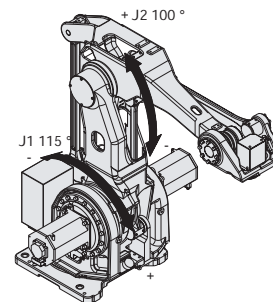
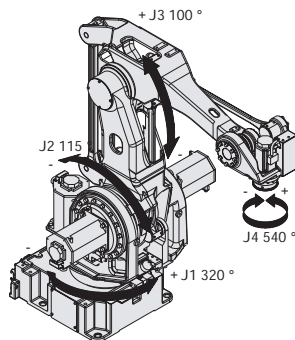
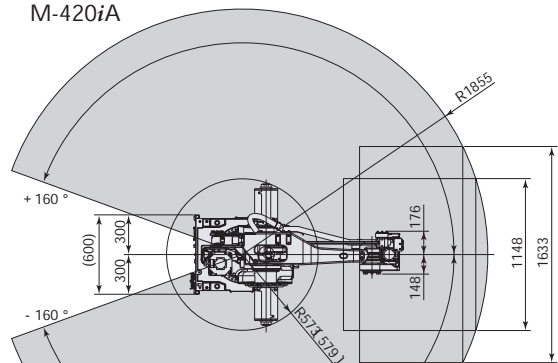
动作区域 Operating Space

机器人的运动 Robot Motion

M-420iA

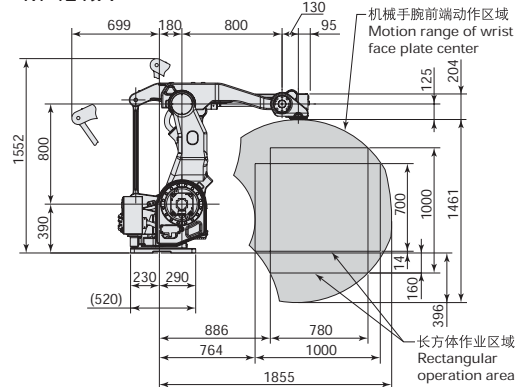
M-420iA

M-421iA



( ) : M-420iA 高速机械手腕规格  
High speed wrist type  
( ) : M-420iA 食品包装规格  
2nd Food type

M-421iA



## 规格 Specifications

| 项目 Item                                       |         | 规格 Specifications   |   |         |
|---|---------|---|---|---------|
|   |         | M-420iA   | M-420iA 高速机械手腕规格<br>High speed wrist type | M-421iA |
| 动作形态 Type                                     |         | 多关节型机器人 Articulated type  |   |         |
| 控制轴 Controlled axes                           |         | 4轴 4 axes (J1, J2, J3, J4)  |   |         |
| 设置条件 Installation                             |         | 地面设置 Floor mount  |   |         |
| 机械手腕部可搬运重量<br>Maximum load capacity at wrist  |         | 40kg  | 30kg                                      | 50kg    |
| 有效范围 Reach                                    |         | 1855mm  |   |         |
| 最大动作速度<br>Maximum speed                       | J1      | 3.14rad/sec (180 deg/sec)   |   | —       |
|   | J2 (J1) | 3.49rad/sec (200 deg/sec)   |   |         |
|   | J3 (J2) | 3.49rad/sec (200 deg/sec)   |   |         |
|   | J4      | 6.11rad/sec (350 deg/sec)   | 12.6rad/sec (720 deg/sec)                 | —       |
| 机械手腕允许负载惯量<br>Allowable load inertia at wrist |         | 2.5kgm <sup>2</sup>   |   |         |
| 位置反复精度 Repeatability                          |         | ±0.5mm  |   |         |
| 机构部重量 Mass of mechanical unit                 |         | 620kg   | 630kg                                     | 520kg   |
| 设置条件 Installation environment                 |         | 环境温度 : 0~45度<br>环境湿度<br>通常 : 在75%RH或以下 注释1)<br>短期 (1个月之内) : 在95%RH或以下<br>振动值 : 0.5G或以下<br>Ambient temperature : 0 ~ 45<br>Ambient humidity<br>Normally : 75%RH or less Note 1)<br>Short term (within 1 month) : 95%RH or less<br>Vibration : 0.5G or less |   |         |

注释1) 不应有结露现象。

注释2) M-420iA 还备有食品包装规格。

Note 1) No dew, nor frost is allowed. Note 2) 2nd Food type is available for M-420iA

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